

Why doesn't EM find good HMM POS-taggers?

Mark Johnson

Microsoft Research Brown University

Bayesian inference for HMMs

- Compare Bayesian methods for estimating HMMs for *unsupervised POS tagging*
 - Gibbs sampling
 - Variational Bayes
 - How do these compare to EM?
- Most words belong to few POS: can a sparse Bayesian prior on $P(w|y)$ capture this?
- KISS – look at bitag HMM models first
- Cf: Goldwater and Griffiths 2007 study semi-supervised Bayesian inference for tritag HMM POS taggers

Main findings

- Bayesian inference finds better POS tags
- By reducing the number of states, EM can do almost as well
- All these methods take hundreds of iterations to stabilize (converge?)
- Wide variation in performance of all models
→ multiple runs to assess performance

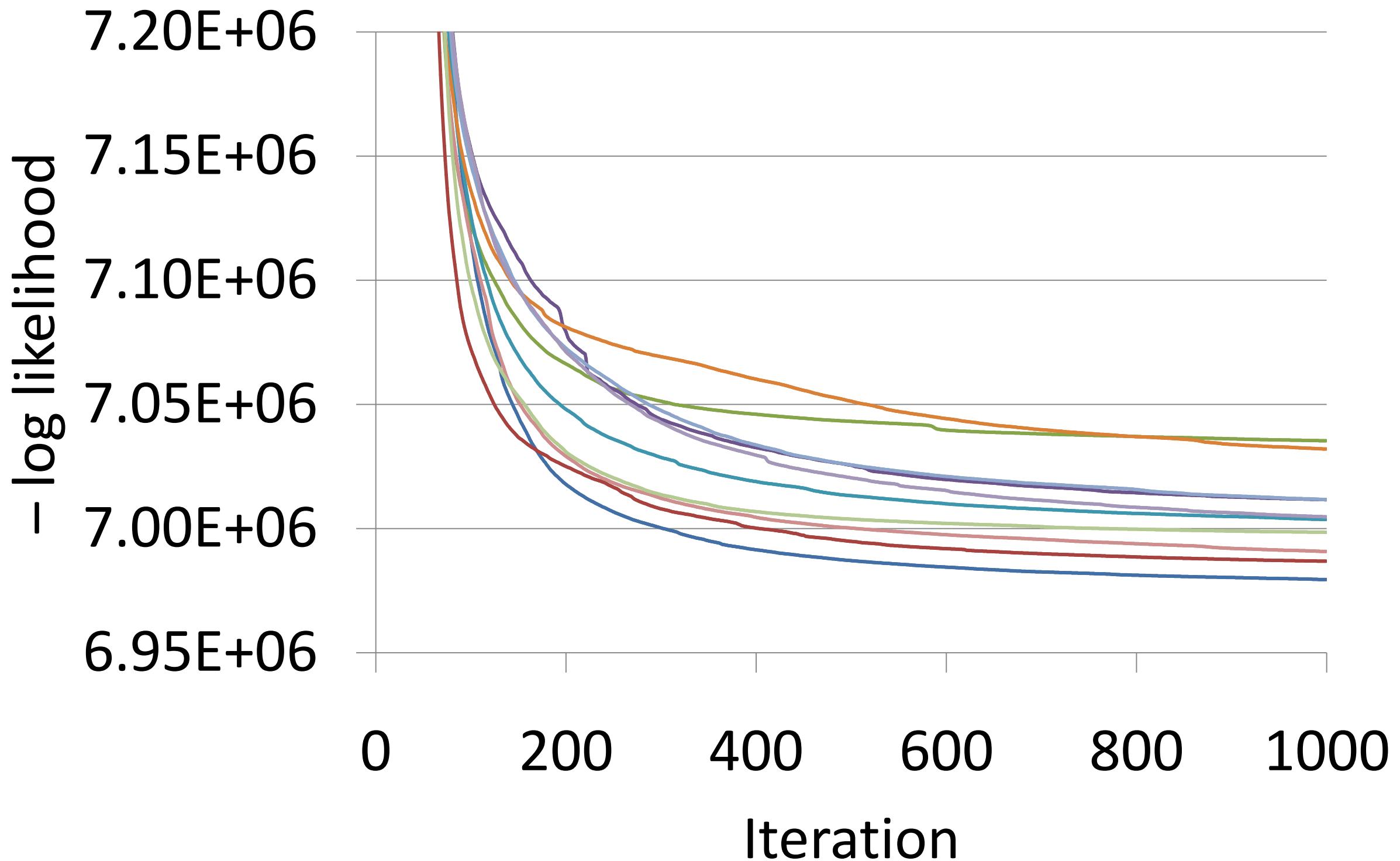
Evaluation methodology

- “Many-to-1” accuracy:
 - Each HMM hidden state y is mapped to the most frequent gold POS tag t it corresponds to
- “1-to-1” accuracy: (Haghghi and Klein 06)
 - Greedily map HMM states to POS tags, under constraint that at most 1 state maps to each tag
- Information-theoretic measures: (Meila 03)
 - $\text{VI}(Y, T) = H(Y|T) + H(T|Y)$
- Max marginal decoding faster and usually better than Viterbi

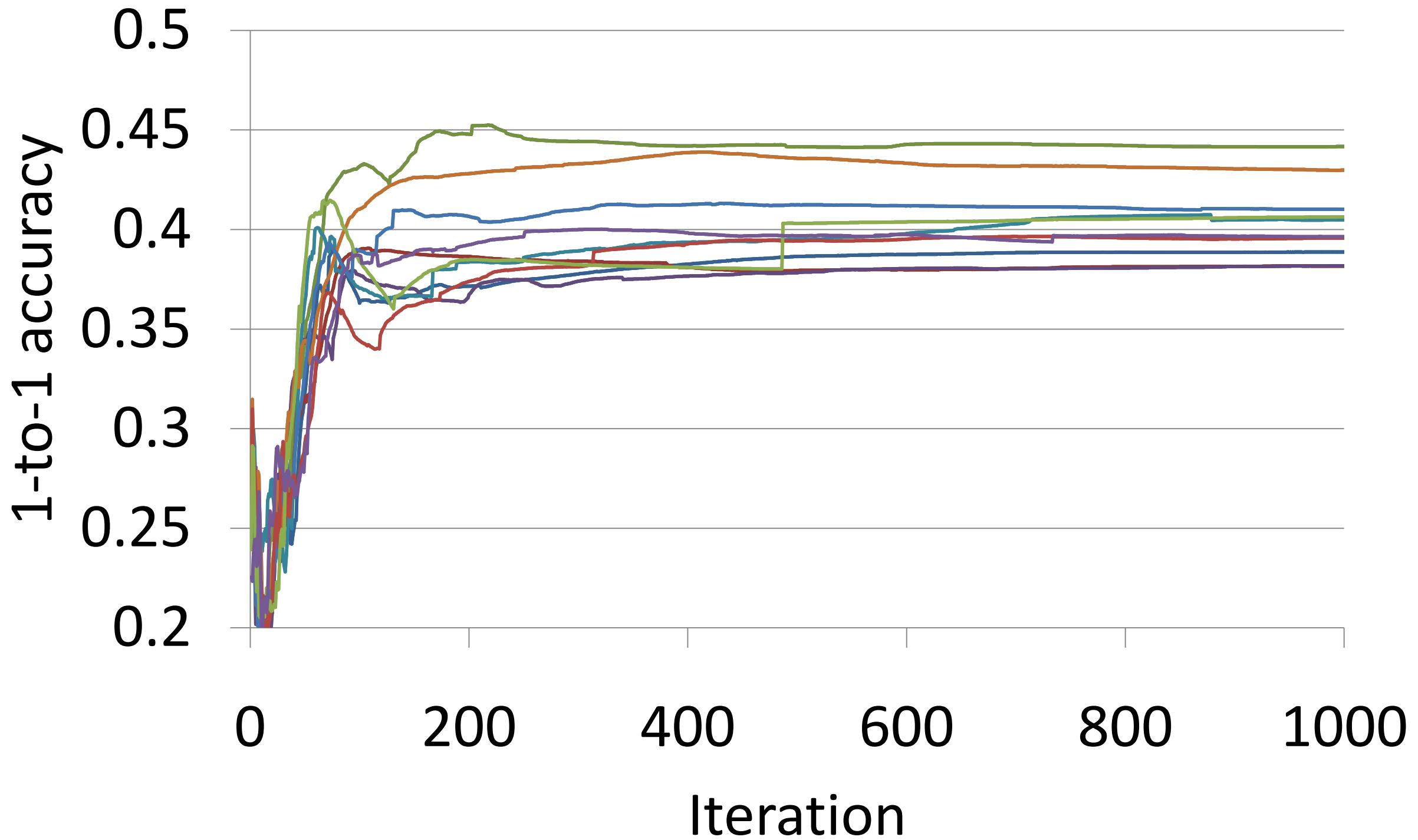
EM via Forward-Backward

- Hmm model: $y_i | y_{i-1} \sim \text{Discrete}(\theta_{y_{i-1}})$
 $x_i | y_i \sim \text{Discrete}(\phi_{y_i})$
- EM iterations: $\theta_{y'|y}^{(l+1)} = E[n_{y',y}] / E[n_y]$
 $\phi_{x|y}^{(l+1)} = E[n_{x,y}] / E[n_y]$
- All expts run on POS tags from WSJ PTB

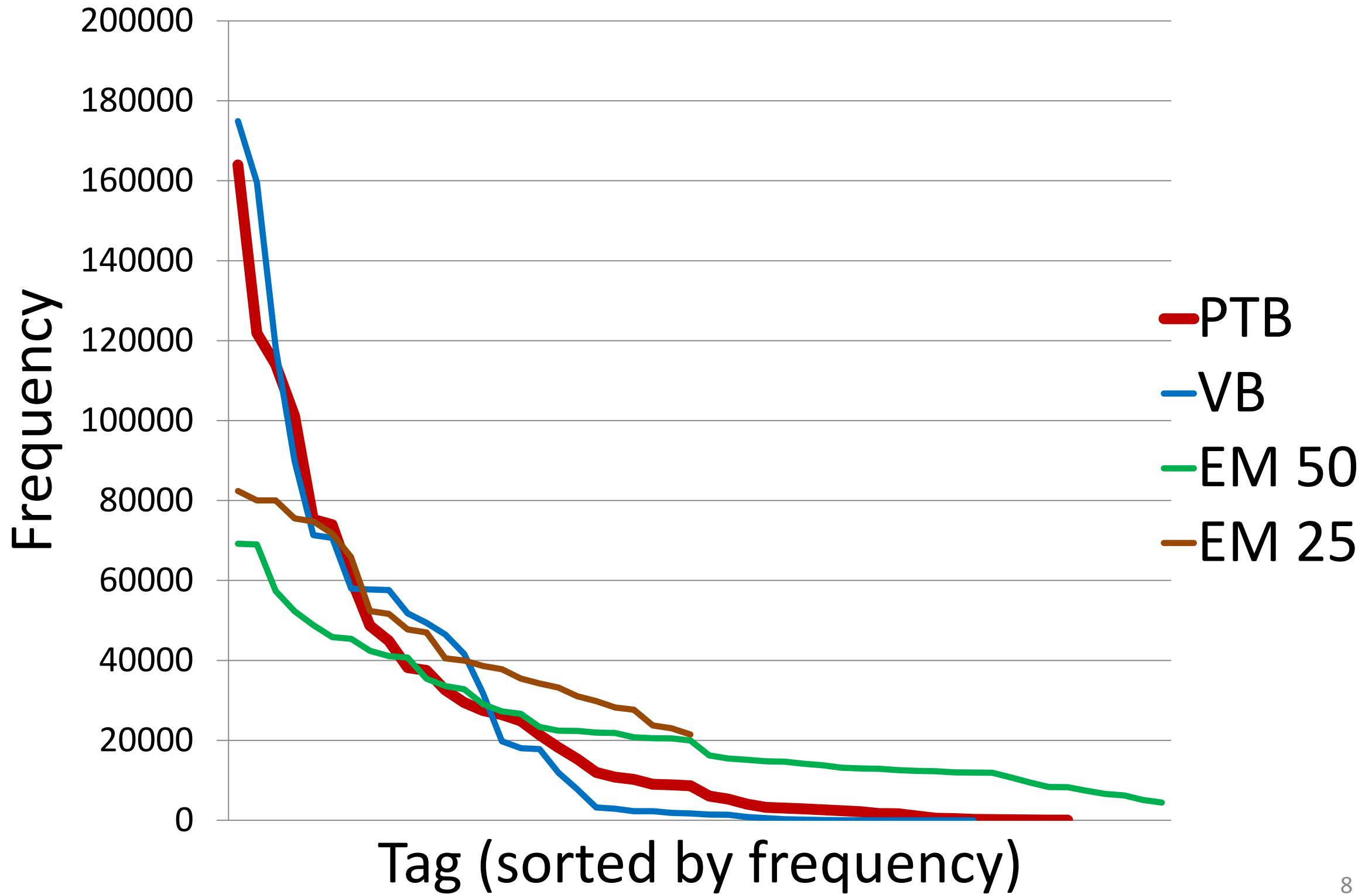
EM is slow to stabilize



EM 1-to-1 accuracy varies widely



EM tag dist less peaked than empirical



Bayesian estimation of HMMs

- HMM with Dirichlet priors on tag→tag and tag→word distributions

$$y_i | y_{i-1} \sim \text{Discrete}(\boldsymbol{\theta}_{y_{i-1}})$$

$$x_i | y_i \sim \text{Discrete}(\boldsymbol{\phi}_{y_i})$$

$$\boldsymbol{\theta}_y | \alpha \sim \text{Dir}(\alpha)$$

$$\boldsymbol{\phi}_y | \beta \sim \text{Dir}(\beta)$$

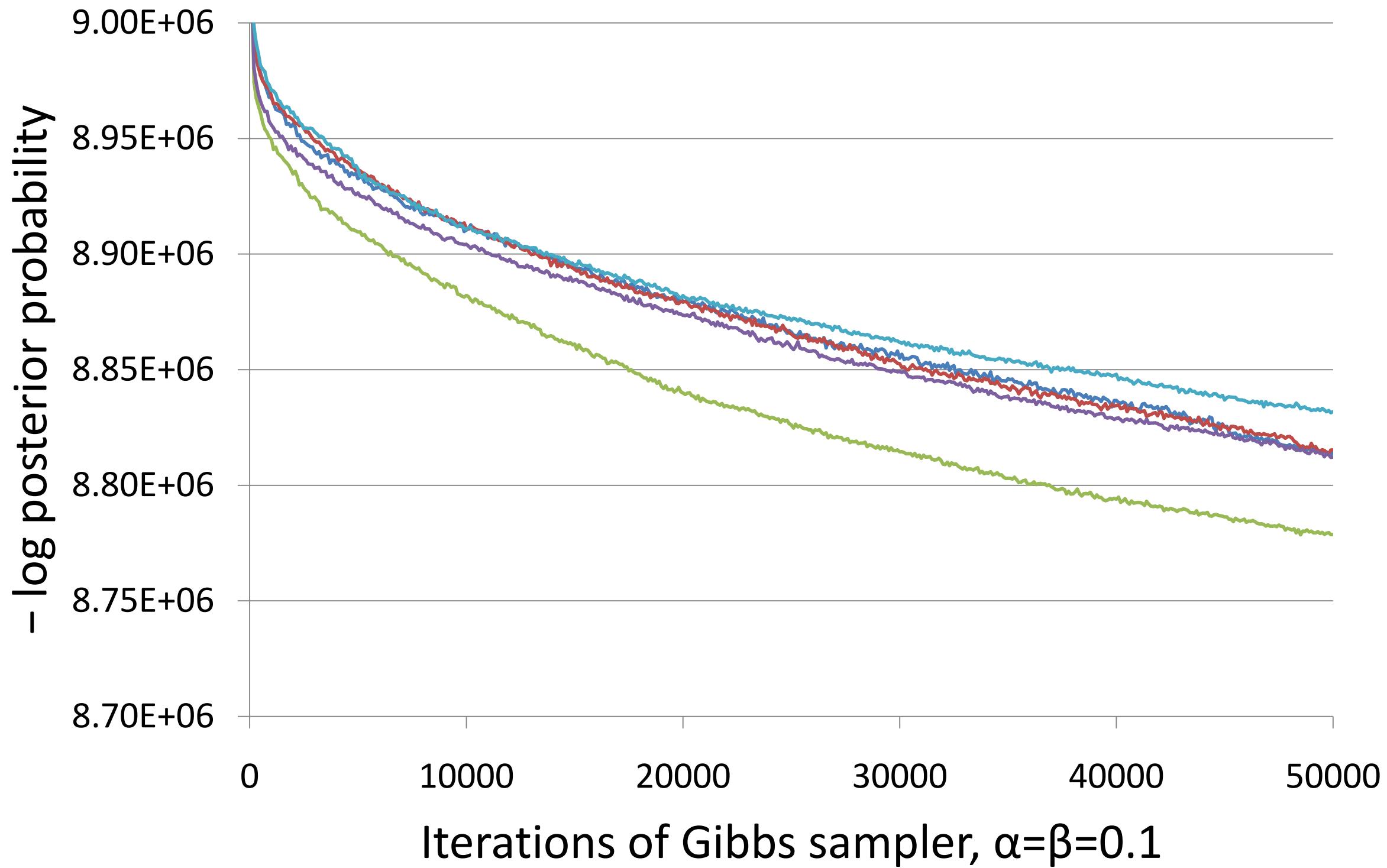
- As Dirichlet parameter approaches zero, prior prefers sparse (more peaked) distributions

Gibbs sampling

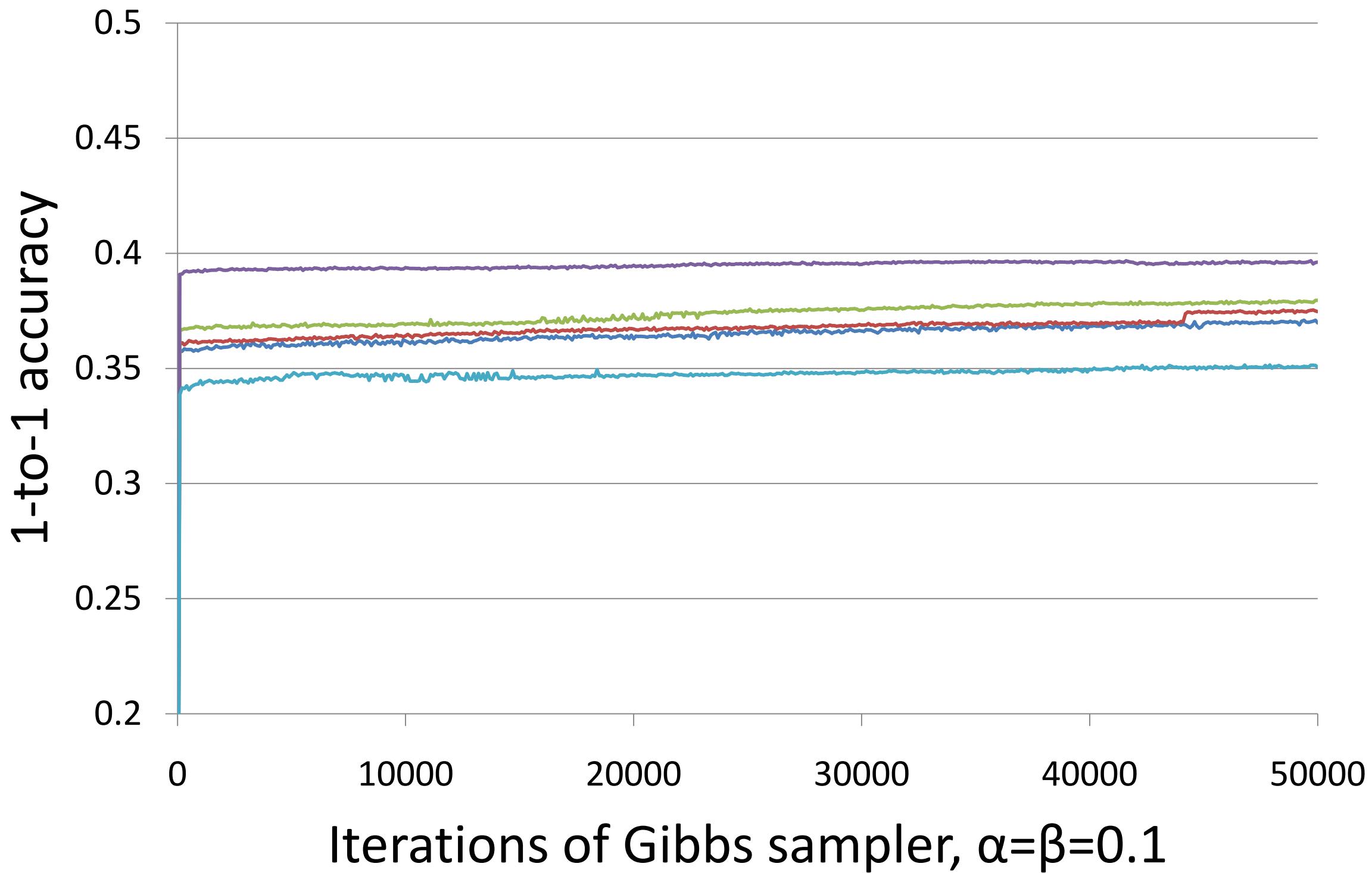
- A Gibbs sampler is a MCMC procedure for sampling from posterior dist $P(\mathbf{y}|\mathbf{x}, \alpha, \beta)$
- Integrate out the θ, ϕ parameters
- Repeatedly sample from $P(y_i | \mathbf{y}_{-i}, \alpha, \beta)$, where \mathbf{y}_{-i} is the vector of all \mathbf{y} except y_i

$$P(y_i | \mathbf{y}_{-i}, \alpha, \beta) \propto \frac{n_{x_i, y_i} + \beta}{n_{y_i} + m\beta} \quad \frac{n_{y_i, y_{i-1}} + \beta}{n_{y_{i-1}} + s\beta} \quad \frac{n_{y_{i+1}, y_i} + I(y_{i-1} = y_i) + \beta}{n_{y_i} + I(y_{i-1} = y_i) + s\beta}$$

Gibbs sampling is even slower



Gibbs stabilizes fast (to poor solns)

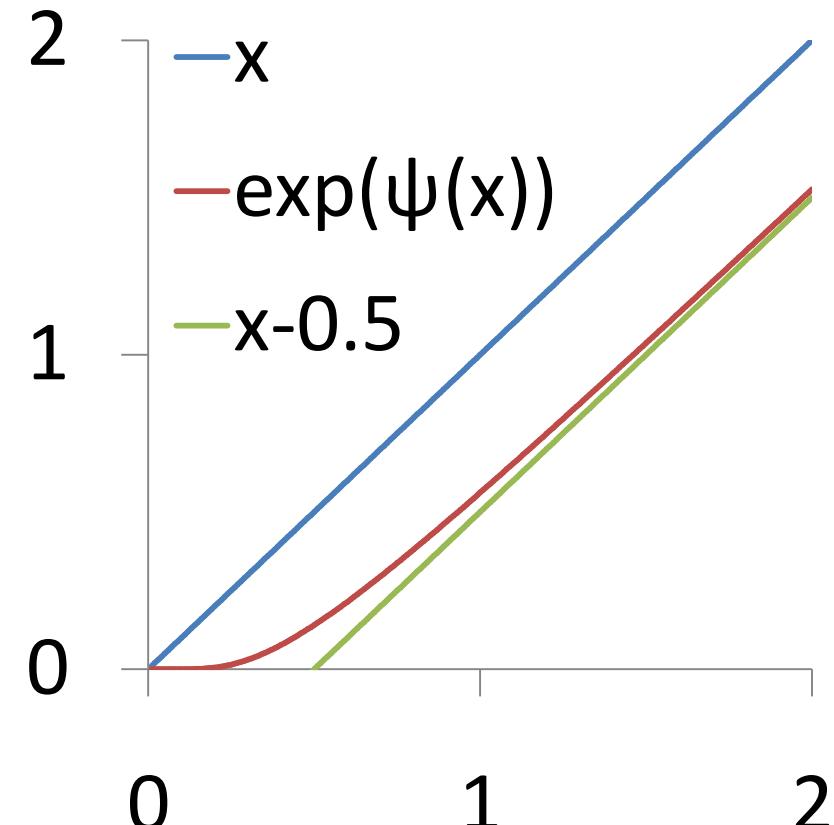


Variational Bayes

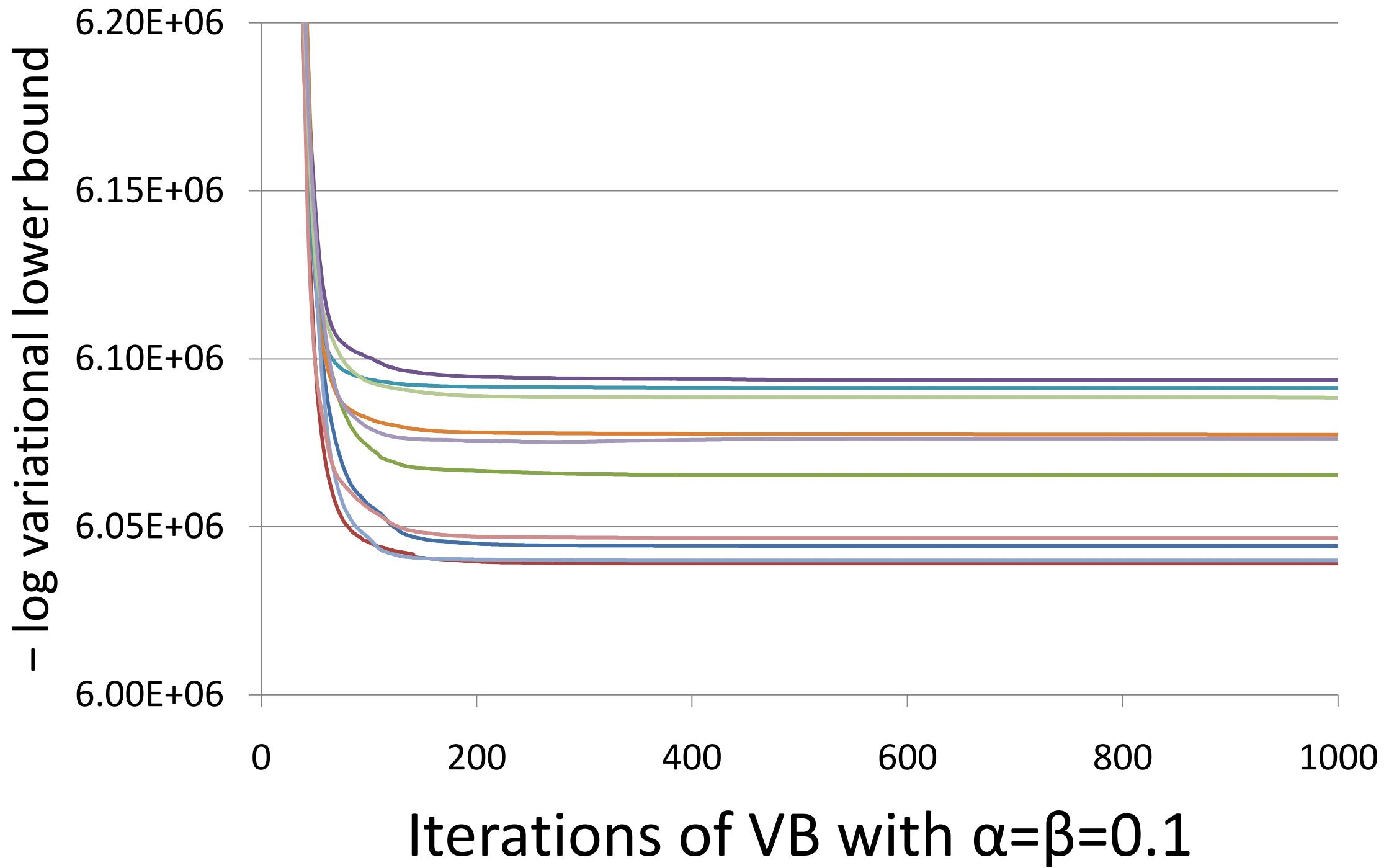
- Variational Bayes approximates the posterior
 $P(y, \theta, \phi | x, \alpha, \beta) \approx Q(y) Q(\theta, \phi)$
(MacKay 97, Beal 03)
- Simple, EM-like procedure:

$$\tilde{\theta}_{y'|y}^{(l+1)} = \exp \Psi(E[n_{y',y}]) / \exp \Psi(E[n_y])$$

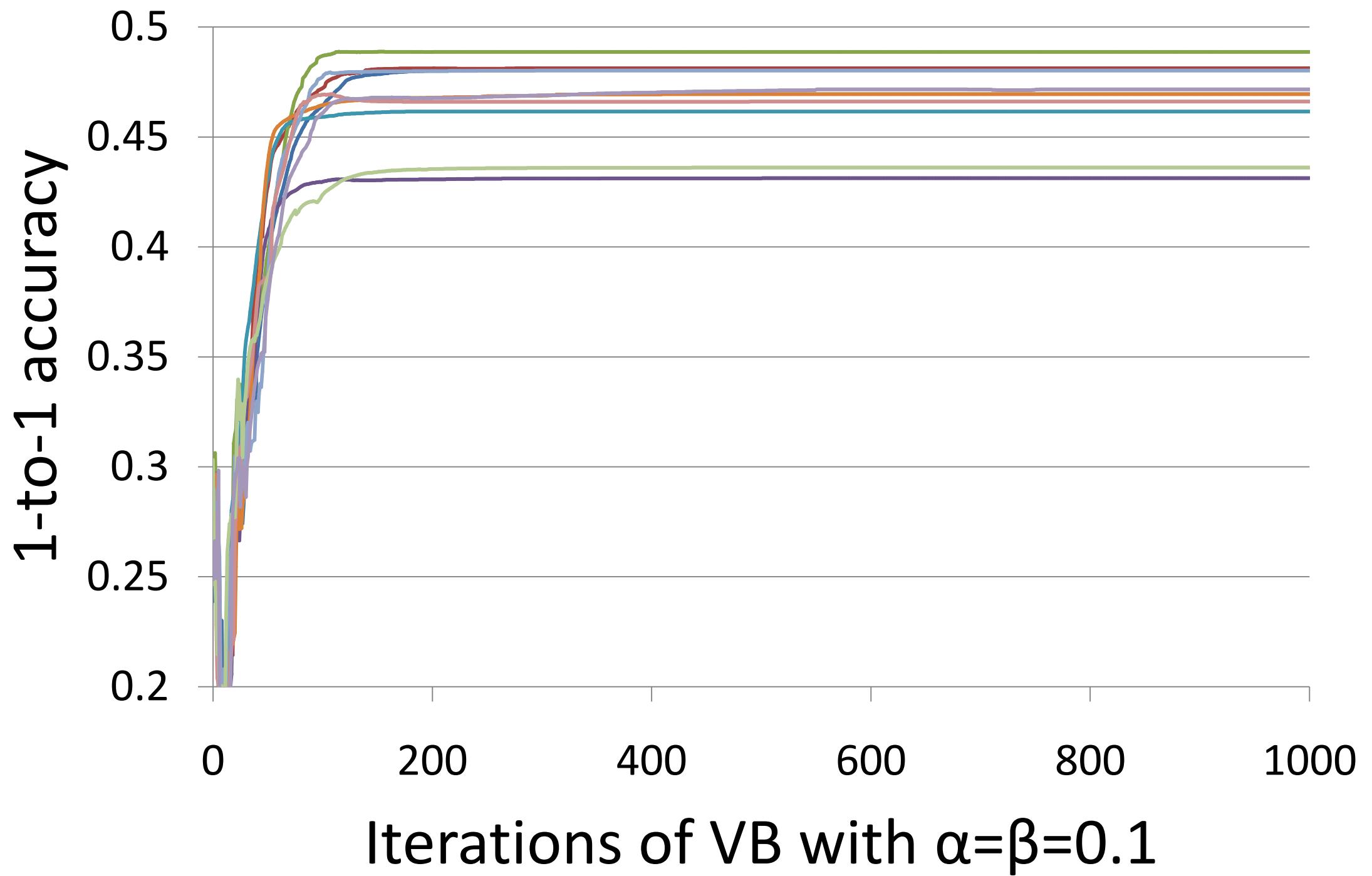
$$\tilde{\phi}_{x|y}^{(l+1)} = \exp \Psi(E[n_{x,y}]) / \exp \Psi(E[n_y])$$



VB posterior seems to stabilize fast



VB 1-to-1 accuracy stabilizes fast



Summary of results

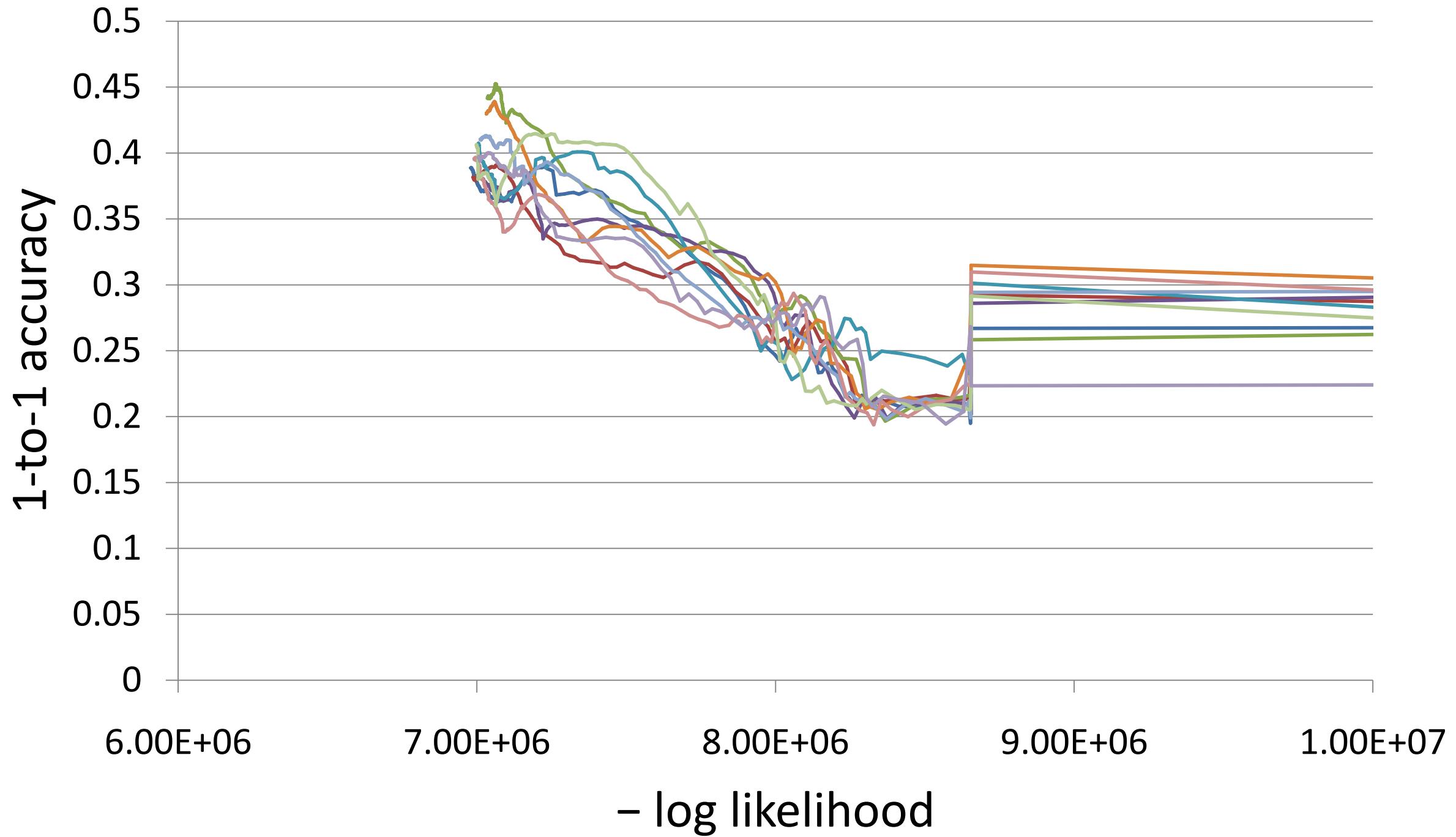
α	β	states	1-to-1	S.D.	many-to-1	S.D.	$VI(T,Y)$	S.D.	$H(T Y)$	S.D.	$H(Y T)$	S.D.	
EM		50	0.40	0.02	0.62	0.01	4.46	0.08	1.75	0.04	2.71	0.06	
VB	0.1	0.1	50	0.47	0.02	0.50	0.02	4.28	0.09	2.39	0.07	1.89	0.06
VB	1E-04	1	50	0.46	0.03	0.50	0.02	4.28	0.11	2.39	0.08	1.90	0.07
VB	0.1	1E-04	50	0.42	0.02	0.60	0.01	4.63	0.07	1.86	0.03	2.77	0.05
VB	1E-04	1E-04	50	0.42	0.02	0.60	0.01	4.62	0.07	1.85	0.03	2.76	0.06
GS	0.1	0.1	50	0.37	0.02	0.51	0.01	5.45	0.07	2.35	0.09	3.20	0.03
GS	1E-04	0.1	50	0.38	0.01	0.51	0.01	5.47	0.04	2.26	0.03	3.22	0.01
GS	0.1	1E-04	50	0.36	0.02	0.49	0.01	5.73	0.05	2.41	0.04	3.31	0.03
GS	1E-04	1E-04	50	0.37	0.02	0.49	0.01	5.74	0.03	2.42	0.02	3.32	0.02
EM		40	0.42	0.03	0.60	0.02	4.37	0.14	1.84	0.07	2.55	0.08	
EM		25	0.46	0.03	0.56	0.02	4.23	0.17	2.05	0.09	2.19	0.08	
EM		10	0.41	0.01	0.43	0.01	4.32	0.04	2.74	0.03	1.58	0.05	

- Griffiths and Goldwater 2007 report $VI = 3.74$ for an unsupervised tritag model using Gibbs sampling, but on a reduced 17-tag set

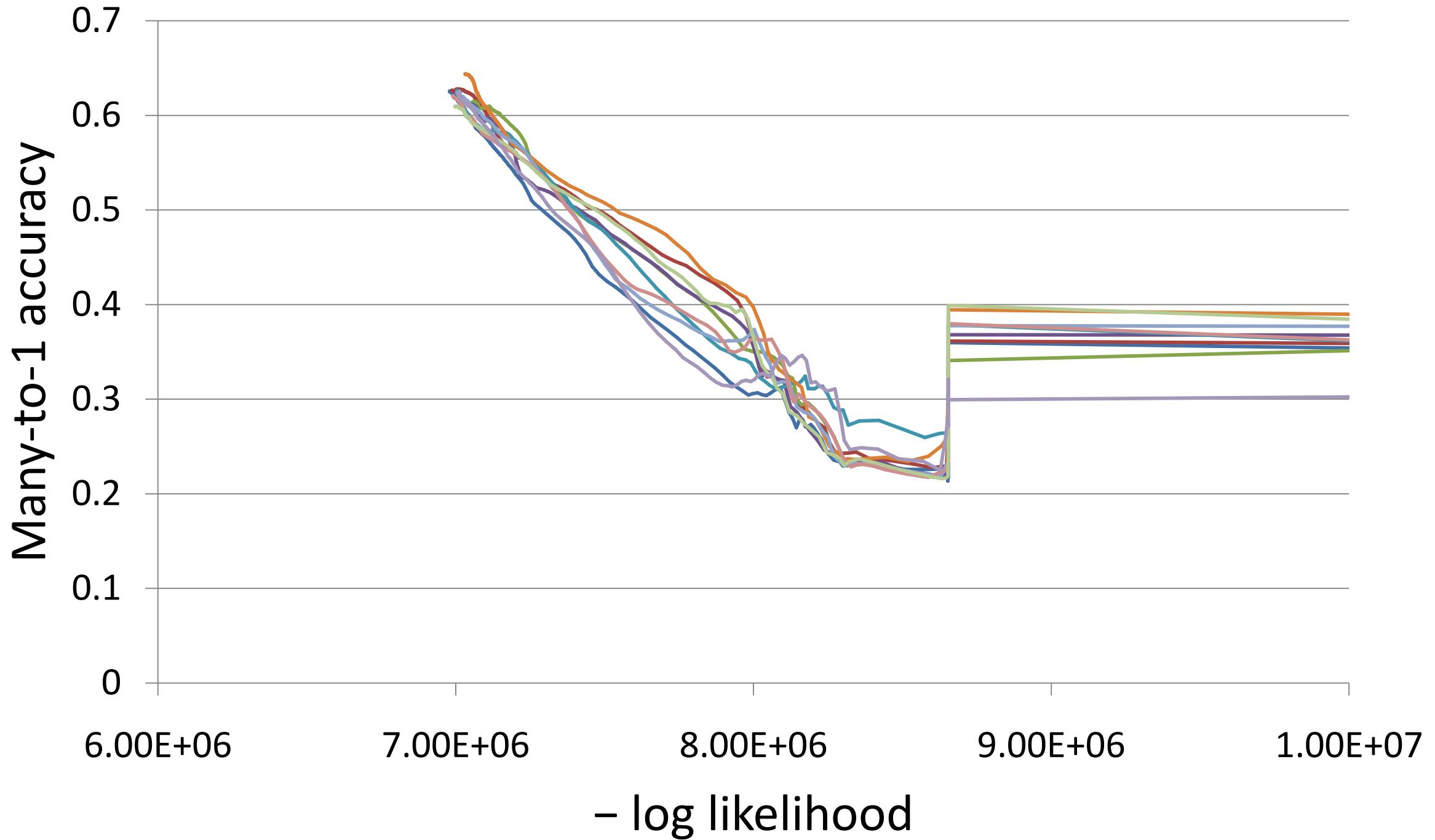
Conclusions

- EM does better if you let it run longer
- Its state distribution is not skewed enough
 - Bayesian priors
 - Reduce the number of states in EM
- Variational Bayes may be faster than Gibbs (or maybe initialization?)
- *Huge performance variance with all estimators* \Rightarrow need multiple runs to assess performance

EM 1-to-1 accuracy vs likelihood



EM many-to-1 accuracy vs likelihood



EM final many-to-1 accuracy vs final likelihood

